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Model-Based Algorithms for Detecting Damage in Ultrasonic Nondestructive Evaluation Measurements

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America

Paris, France

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Model-Based Algorithms for Detecting Damage in Ultrasonic Nondestructive Evaluation Measurements July 2, 2008



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Engineering/NSED/Systems and Decision Sciences Section

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We Have an Interdisciplinary Team

- Graham Thomas - ENG/MMED
 - Project Management
 - NDE, materials characterization
- Chris Robbins - ENG/NSED
 - Program Management
 - Data acquisition, hardware, signal processing software, NDE
- Grace Clark - ENG/NSED
 - Image/signal processing, target/pattern recognition, sensor data fusion, NDE
- Katherine Wade - ENG/NSED
 - Signal processing software and testing



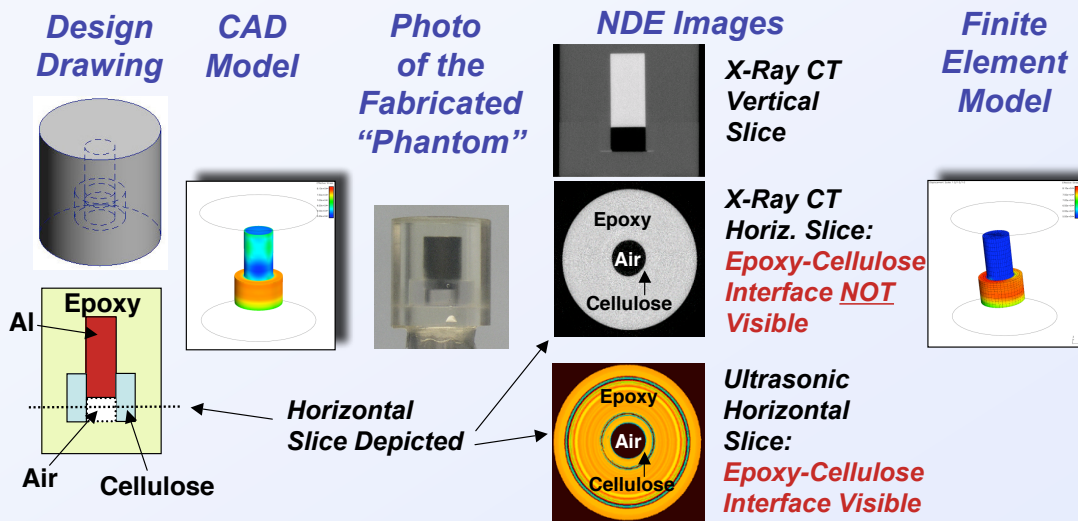
Agenda

- Introduction
 - The Damage Detection Problem
 - Ultrasonic NDE (*As-Built Modeling*)
 - Motivated by Time Domain Reflectometry for Cables
 - This is work in progress
- Technical Approach - *Model-Based Damage Detection*
- Damage Detection Processing Results
 - Ultrasonic NDE
 - TDR for Cables
- Discussion

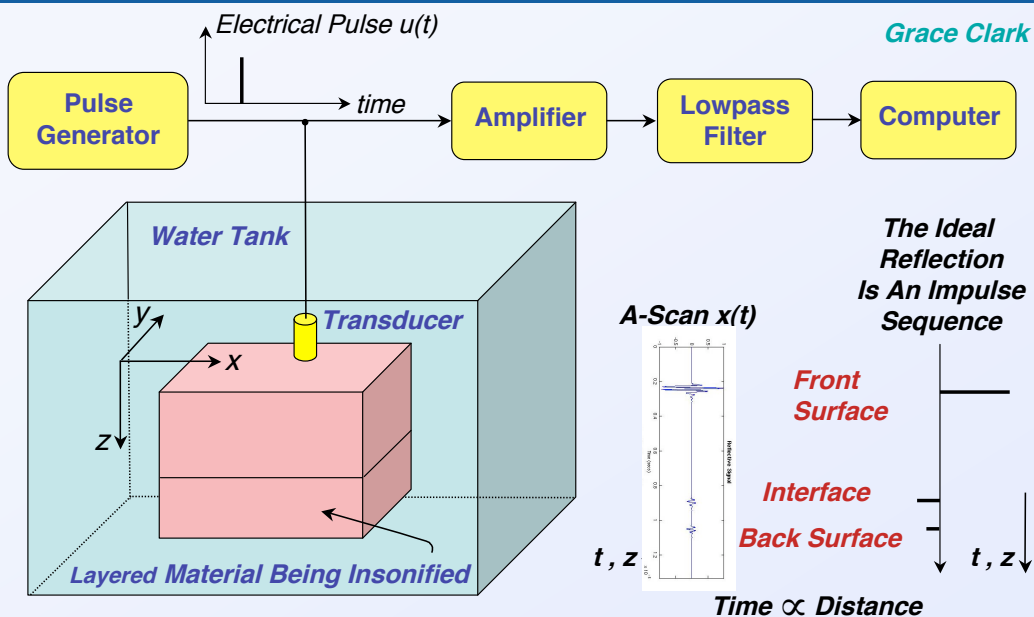


“As-Built Modeling” is Used to Compare Mechanical Objects:
“As-Designed,” “As-Built,” “As Inspected After Use”

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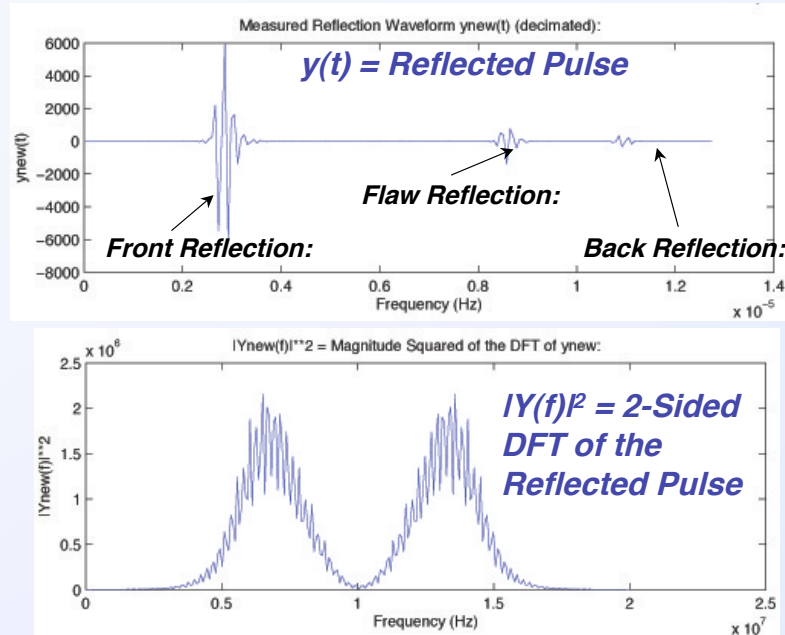
Ultrasonic Pulse-Echo Signals (A-Scans) Are Distorted
By the Transducer and the Propagation Paths (“Ringing”)



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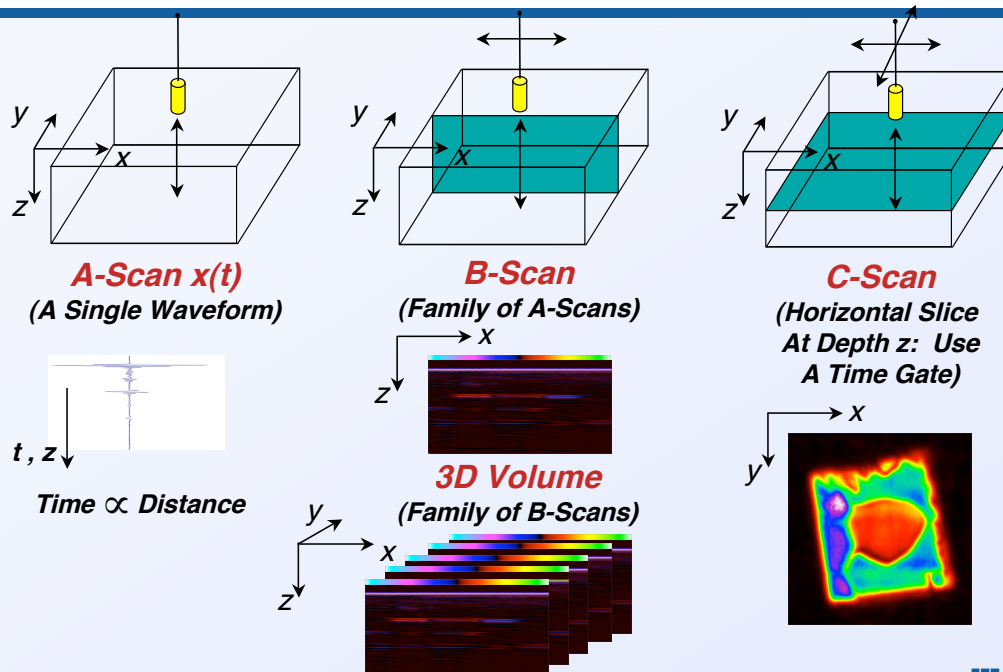


Ultrasonic Pulses Are **Bandlimited** by the Transducer
 \Rightarrow The Pulses "**Ring**", Reducing Spatial Resolution

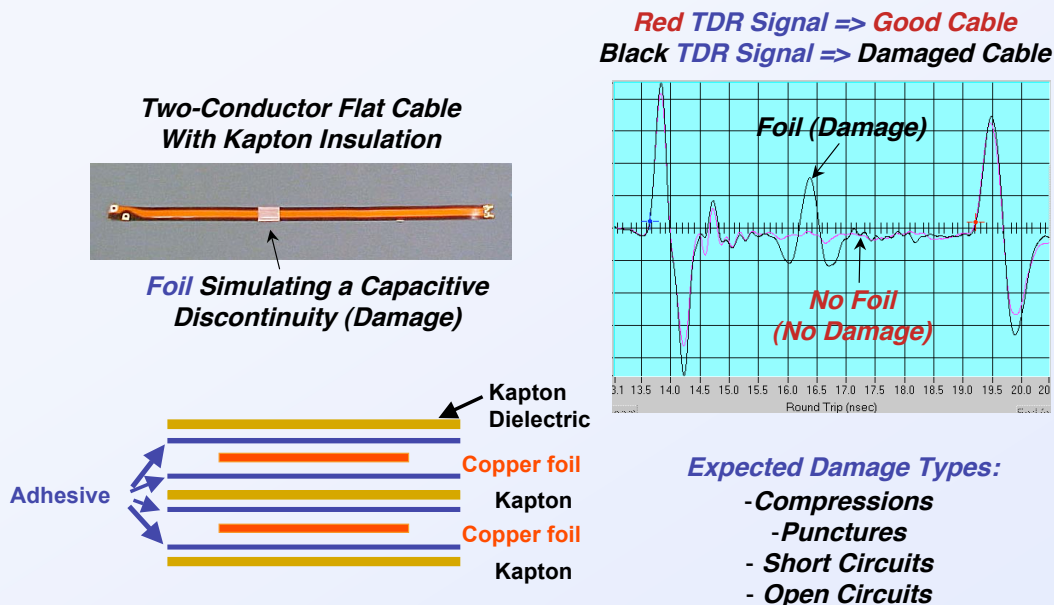


We Define Ultrasonic **A-, B-, and C-Scans** Used in
 Nondestructive Evaluation (NDE) Studies:

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We Are Testing Two-Conductor Flat Cables With Kapton Insulation - For Dielectric Anomalies



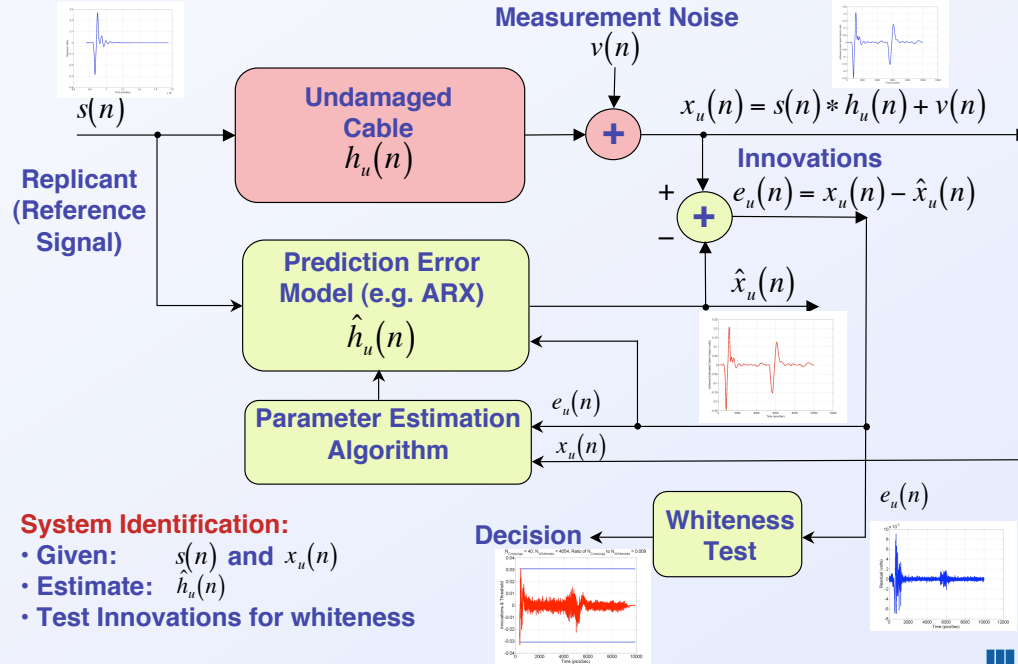
The Model-Based Damage Detection Approach: Detect a Model Mismatch if Damage is Present

- Exploit the fact that the measurements are reasonably repeatable.
- Build a forward model of the dynamic system (cable) for the case in which **NO DAMAGE** exists
- Whiteness Testing on the *Innovations (Errors)*:
Estimate the output of the actual system using measurements from a dynamic test.
 - If **no damage** exists, the model will match the measurements, so the “innovations” (errors) will be **statistically white**.
 - If a **damage** exists, the model will not match the measurements, so the “innovations” (errors) will **not be statistically white**.
- Weighted Sum Square Residuals (WSSR) Test:
The WSSR provides a single metric for the model mismatch



Step #1: System Identification to Estimate the Dynamic Model of the Undamaged Cable

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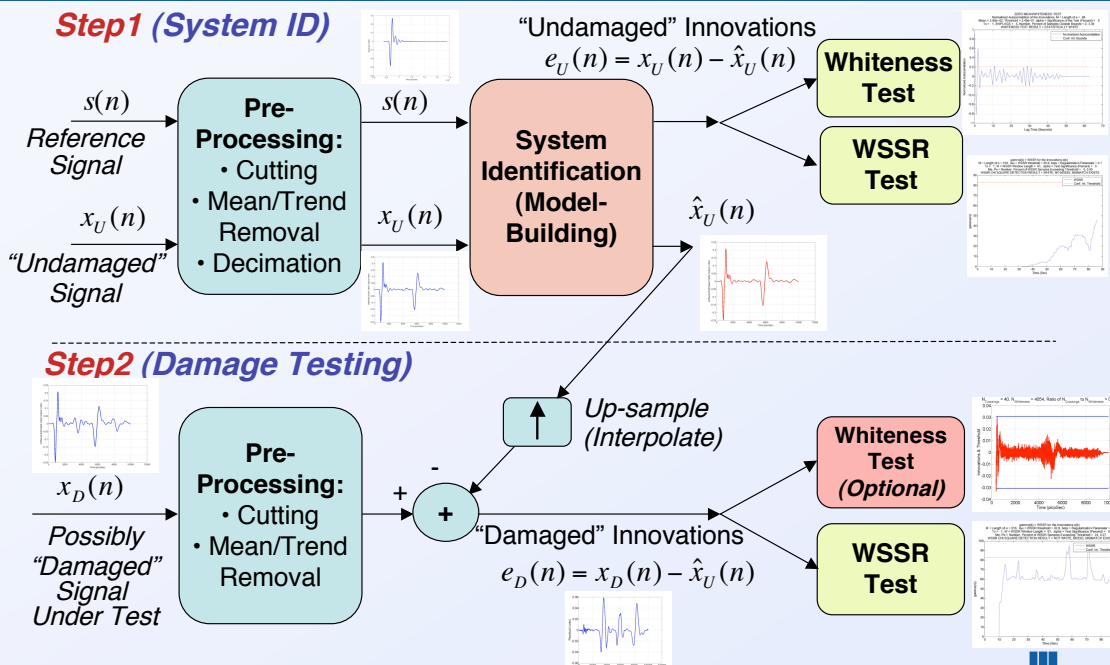
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Step1 (System ID) is Done “Offline”

Step2 (Damage Testing) is Done “Online”



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The Form of the Linear System Model is “ARX” = “Auto-Regressive with Exogenous Input”

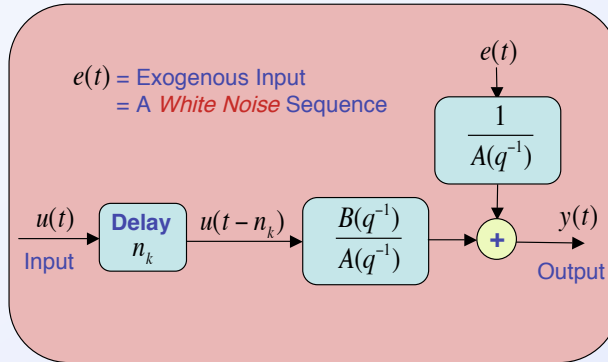
$$y(t) = \frac{B(q^{-1})}{A(q^{-1})} u(t - nk) + \frac{1}{A(q^{-1})} e(t)$$

Where:

$$A(z) = 1 + a_1 q^{-1} + a_2 q^{-2} \cdots + a_{N_a} q^{-N_a}$$

$$B(z) = b_0 + b_1 q^{-1} + b_2 q^{-2} \cdots + b_{N_b} q^{-N_b}$$

q^{-1} = Delay Operator



The model parameters are estimated using a least squares algorithm.

- Solve an over-determined set of linear equations
- Solve using QR factorization algorithm
- The regression matrix is formed so that only measured quantities are used (no fill-out with zeros).



Scalar WSSR (Weighted Sum Squared Residuals) Test For a Scalar Measurement ($p = 1$)

Given the innovations signal $e(n)$

We define the scalar WSSR test statistic at time index n :

$$\gamma(n) = \sum_{j=n-W+1}^n \frac{e^2(j)}{V(j)}, \quad \text{for } n \geq W$$

Note: We estimate WSSR over a finite sliding window of length W samples.

Where:

$$V(n) = \frac{1}{W} \sum_{j=n-W+1}^n [e^2(j) - \bar{e}(j)]^2, \quad \text{for } n \geq W$$

Sample variance
over the sliding window

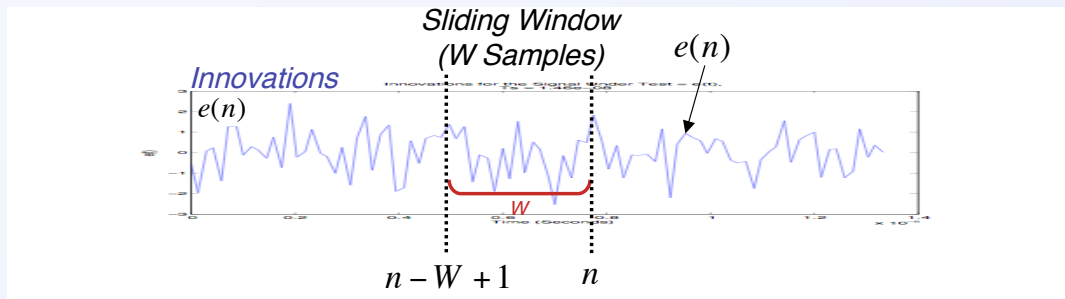
$$\bar{e}(n) = \frac{1}{W} \sum_{j=n-W+1}^n e(j), \quad \text{for } n \geq W$$

Sample mean
over the sliding window



Scalar WSSR is Calculated Using a Sliding Window Over the Innovations Sequence $e(n)$

WSSR = “Weighted Sum Squared Residuals”



$$\gamma(n) = \sum_{j=n-W+1}^n \frac{e^2(j)}{V(j)}, \quad \text{for } n \geq W$$

WSSR is a useful test statistic for detecting an abrupt change, or “jump” in the innovations



Define the WSSR Hypothesis Test

By defining a threshold (later), the WSSR test becomes:

$$\text{If } \gamma(n) \begin{matrix} \geq H_1 \\ < H_0 \end{matrix} \tau, \quad (\tau = \text{Decision Threshold})$$

Read this as follows:

If $\gamma(n) \geq \tau$, then H_1 is true

If $\gamma(n) < \tau$, then H_0 is true



WSSR Test

For a scalar measurement ($p = 1$) (Continued)

For the null hypothesis H_0 , the WSSR is chi square distributed:

$$\gamma(n) \sim \chi^2(W)$$

However, for $W > 30$, the WSSR is approximately normally distributed:

$$\gamma(n) \sim N(W, 2W)$$

At the significance level α , the probability of rejecting the null Hypothesis (detecting a jump) is:

$$P\left(\left|\frac{\gamma(n) - W}{\sqrt{2W}}\right| > \left|\frac{\tau - W}{\sqrt{2W}}\right|\right) = \alpha$$



WSSR Hypothesis Test (Continued)

At the significance level α , we can create a confidence interval test:

$$\text{For } H_0: \quad P[\gamma(n) < \tau] = 1 - \alpha = .95$$

$$\text{For } H_1: \quad P[\gamma(n) \geq \tau] = \alpha = .05$$

For a significance level $\alpha = .05$, the threshold is:

$$\tau = W + 1.96\sqrt{2W}$$



The Scalar WSSR Confidence Interval Threshold is Parameterized by the Window Length W

Summary of the WSSR Test for Significance $\alpha = .05$:

$$\gamma(n) = \sum_{j=n-W+1}^n \frac{e^2(j)}{V(j)}, \quad \text{for } n \geq W$$

$$V(n) = \frac{1}{W} \sum_{j=n-W+1}^n [e^2(j) - \bar{e}(j)]^2, \quad \text{for } n \geq W$$

$$\bar{e}(n) = \frac{1}{W} \sum_{j=n-W+1}^n e(j), \quad \text{for } n \geq W$$

$$\tau = W + 1.96\sqrt{2W}$$

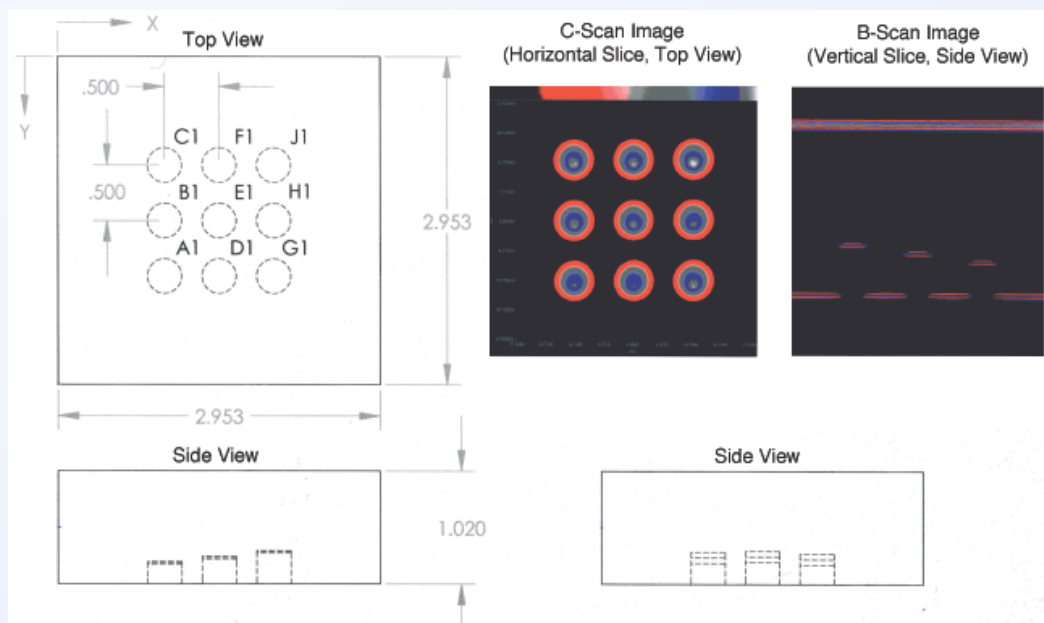
If $\gamma(n) \geq H_1 \tau$, $(\tau = \text{Decision Threshold})$
 $< H_0$

In practice, we implement the WSSR test as follows:

- Let F_E = Fraction of samples of $\gamma(n)$ that exceed the threshold
- If $F_E \leq \alpha$, Declare H_0 is true (innovations are white, no jump)
- If $F_E > \alpha$, Declare H_1 is true (innovations are not white, jump)



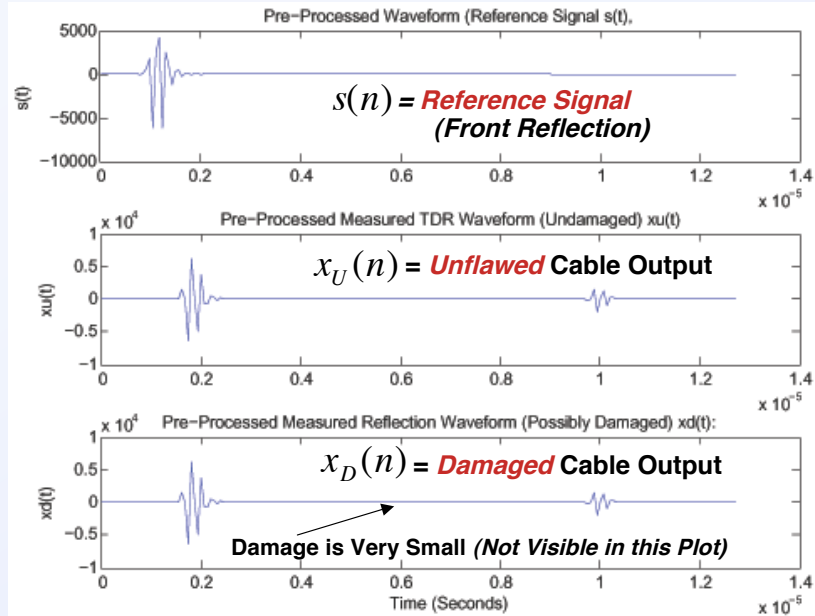
We Constructed a “Phantom” Part - *Aluminum Block* Containing *Flat-Bottom Holes*



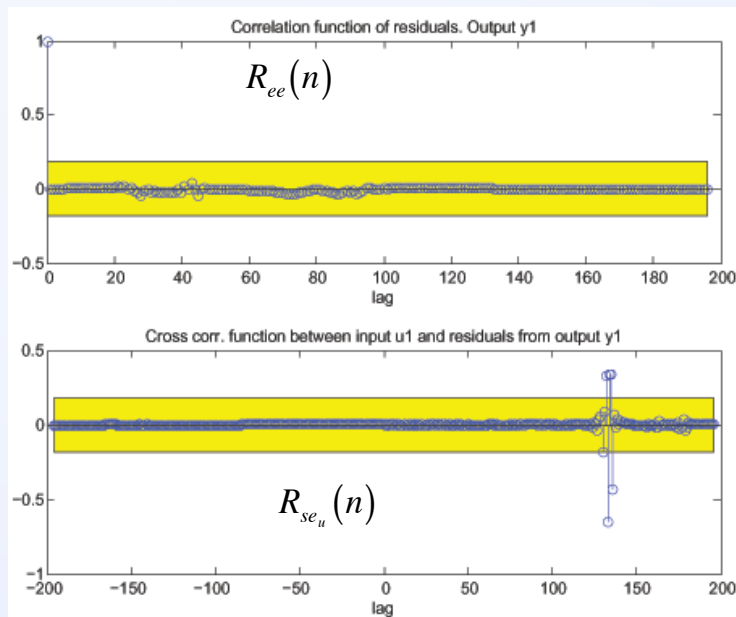
System Identification: Preprocessed Signals

$$f_s = 1.0e8 \text{ Hz}$$

$$T_s = 1.0e-8 \text{ sec}$$



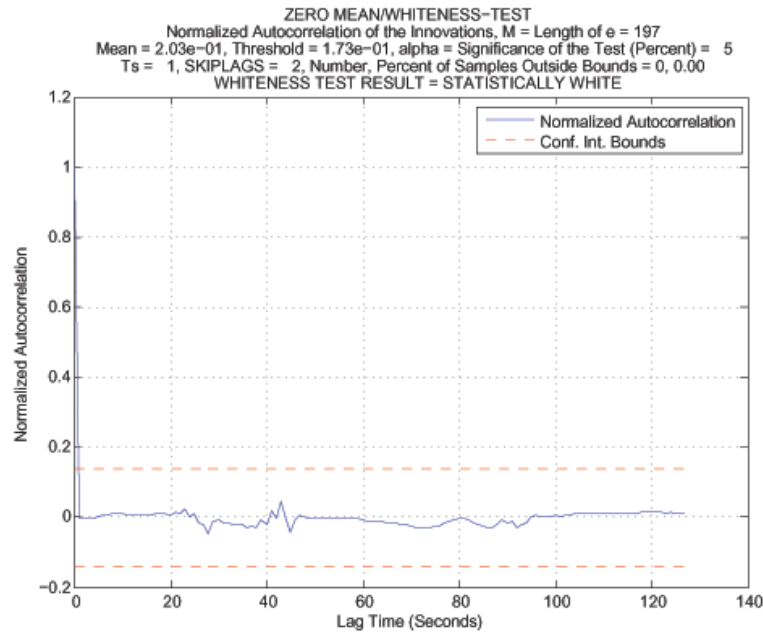
System Identification: Correlation Tests are Satisfactory



UT1a_WT_euC

System Identification Whiteness Test Result = *White*

Model:
arx(30,29,1)



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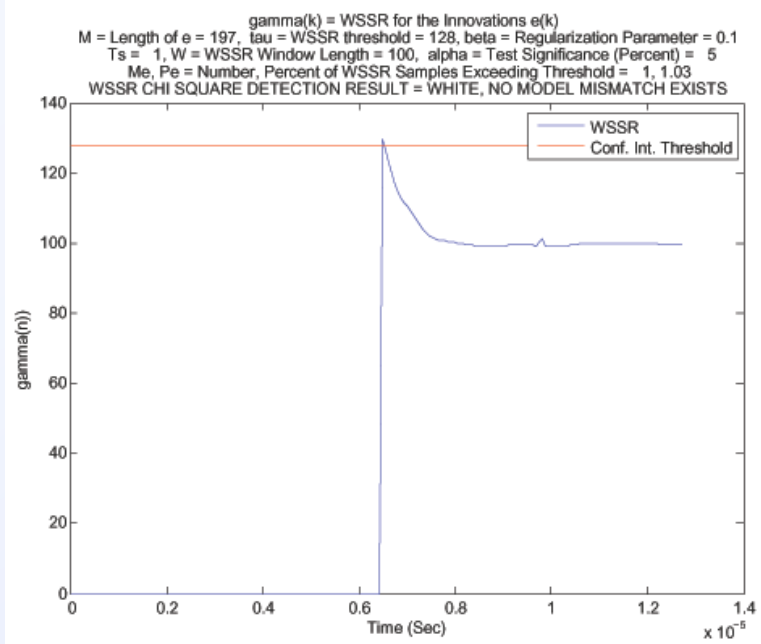
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UT1a_WSSR_euC.pdf

System Identification WSSR Test Result = *No Model Mismatch!*



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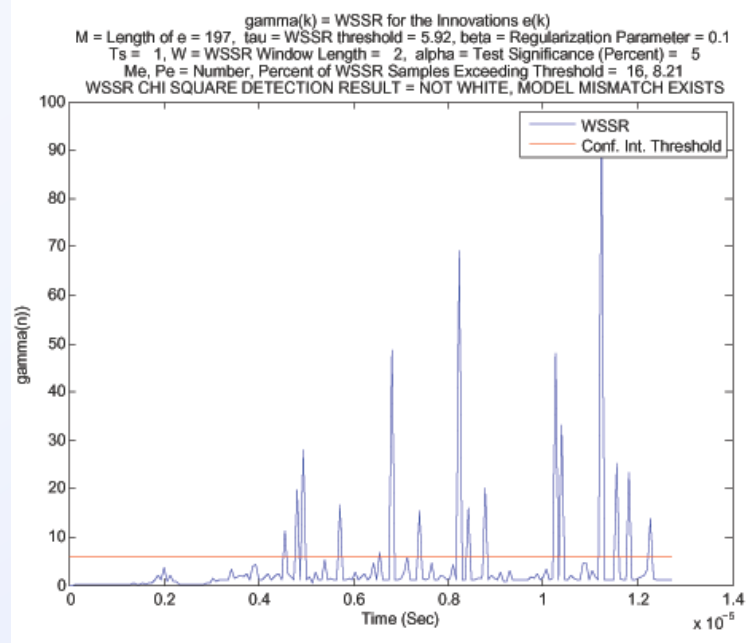
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“Minor Damage” WSSR Result = *Model Mismatch!*



Conclusions & Future Work

- Basic algorithms were validated with real signals
 - Ultrasonic NDE data
 - TDR data - Receiver Operating Characteristic (ROC) curves and Confidence Intervals

Future Work:

- Receiver Operating Characteristic (ROC) Curves for the Ultrasonic data
- More repeatability studies (test the hardware)
- More controlled experiments with known damage
- More studies with various types of damage
- Compare with other approaches



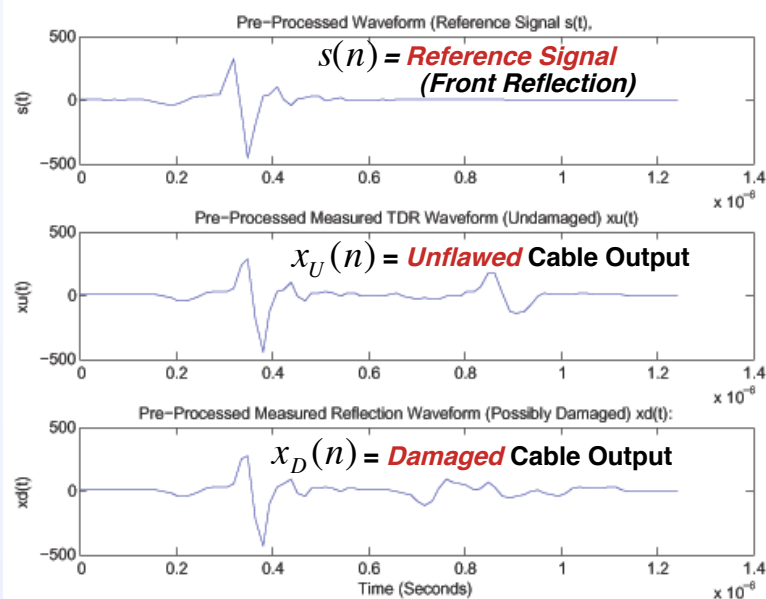
Contingency VG's



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[E1_s_xu_xdC.pdf](#)

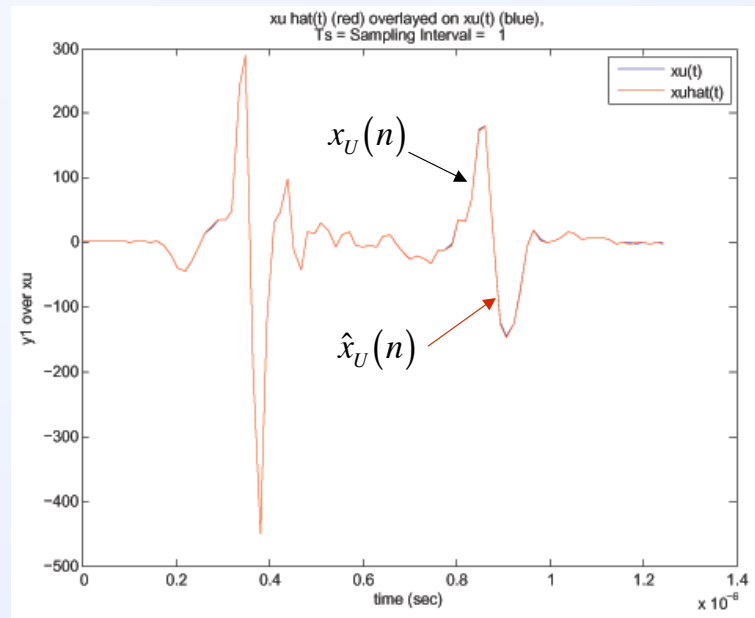
System Identification: Preprocessed Signals



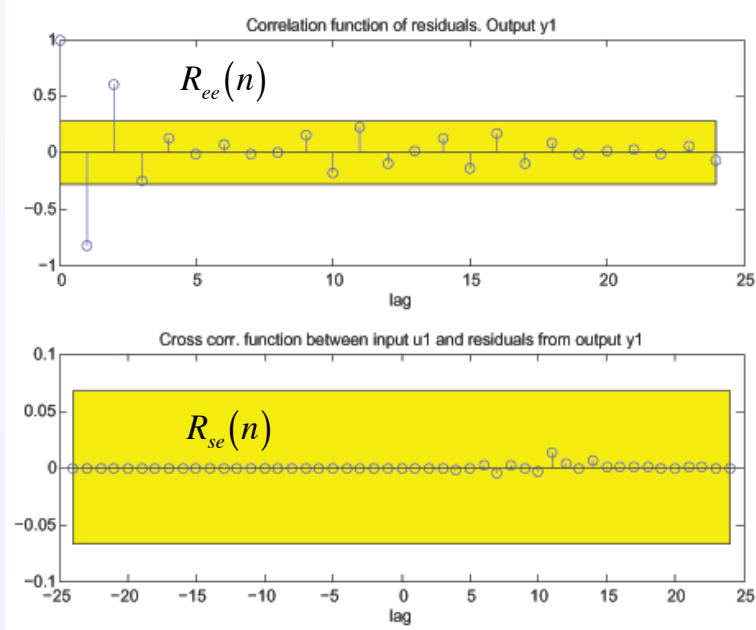
**Example:
Major
Damage**



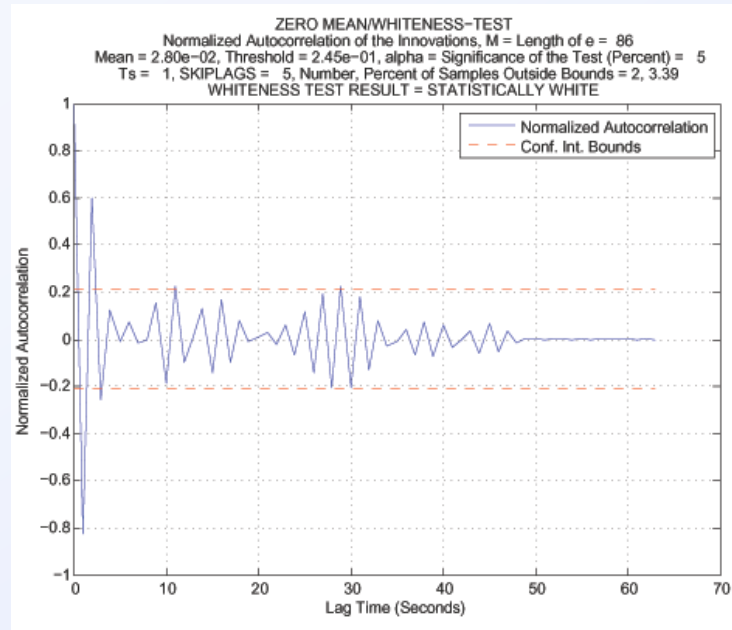
System Identification: *The Model Fit is Good*



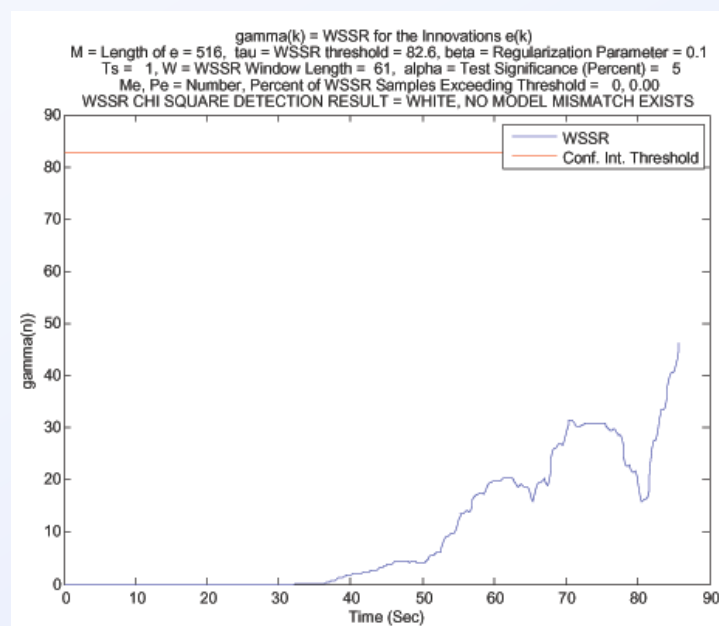
System Identification: *Correlation Tests are Satisfactory*



System Identification Whiteness Test Result = *White*



System Identification WSSR Test Result = *No Model Mismatch!*



We Acquired an Ensemble of Real Signals for Processing

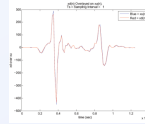
The PIU was never disconnected between acquisitions

Experiment E1: Data from 2_13_07

UNDAMAGED

Reference Signals (*Undamaged*):

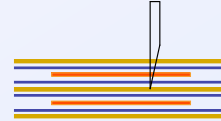
refa, refb, refc



MINOR DAMAGE

Minor Damage (*pin hole, knife present, no short*):

minor1a, minor1b, minor1c



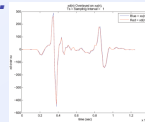
Minor Damage (*pin hole, knife removed, no short*):

minor2a, minor2b, minor2c



Minor Damage (*pin hole, knife removed, cable rubbed to remove short*):

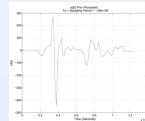
minor3a, minor3b, minor3c



MAJOR DAMAGE

Major Damage (*pin hole, knife removed, conductors shorted*):

major1a, major1b, major1c



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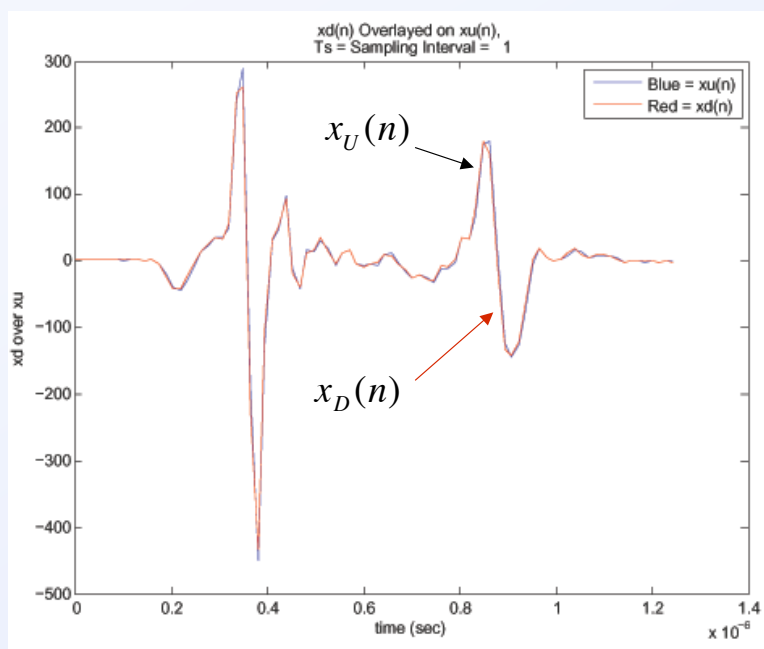
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E1_xd_m3a_xuC.pdf

"Minor3 Damage": Damage Is Difficult to Distinguish Visually



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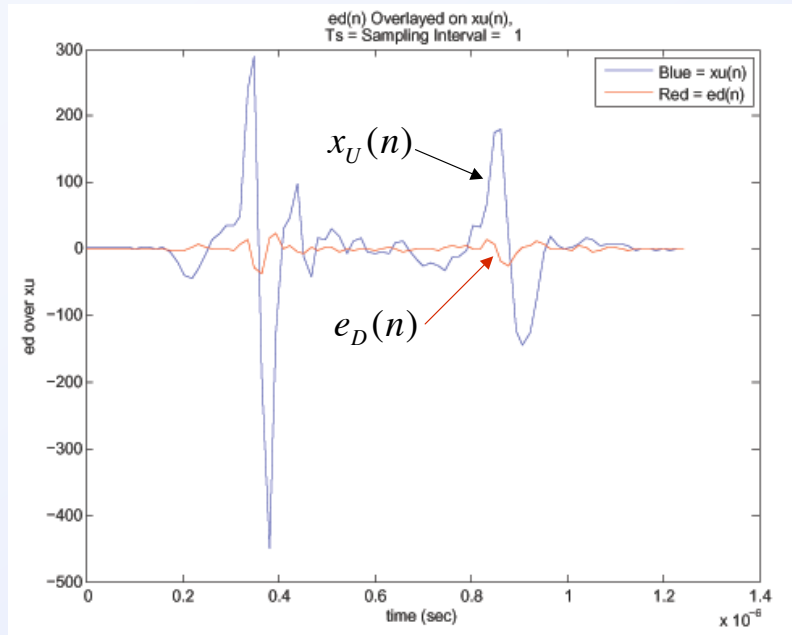
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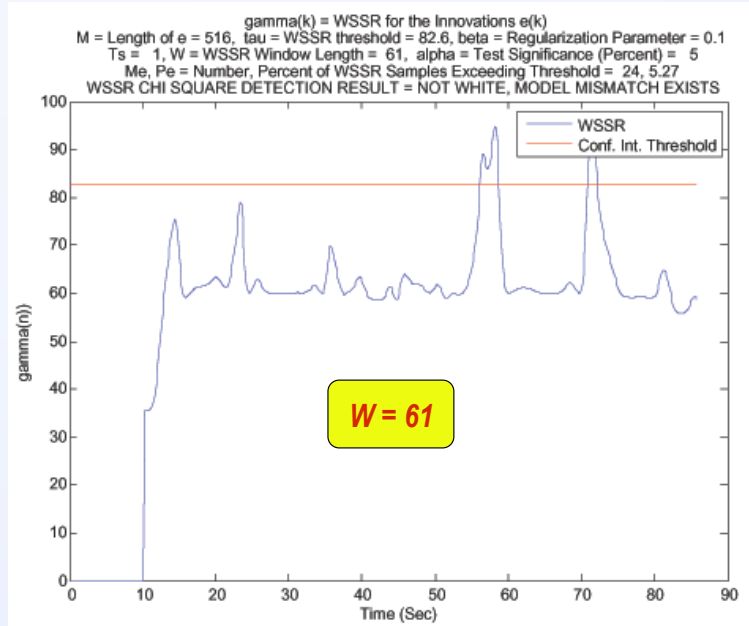


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Minor3 Damage: The Innovations are Small, But Correlated



“Minor3 Damage” WSSR Result = Model Mismatch!



Minor3a,b,c Damage

Receiver Operating Characteristic (ROC) Curve = **Perfect**

